



We fascinate and inspire people with ideas and innovations to shape the future's responsible logistics together.





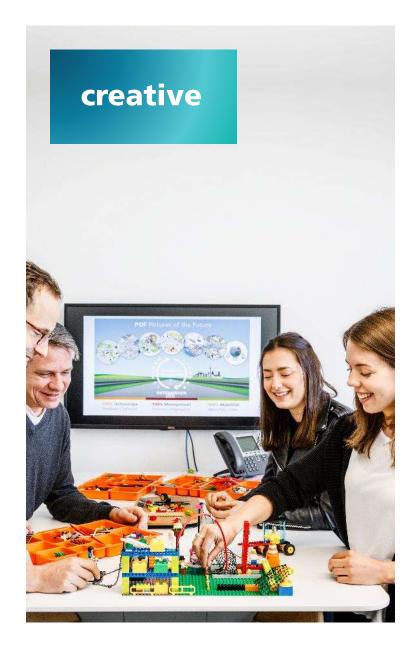
100% Mobility

Prof. Dr.-Ing. Uwe Clausen Humans | Goods 100% Technology

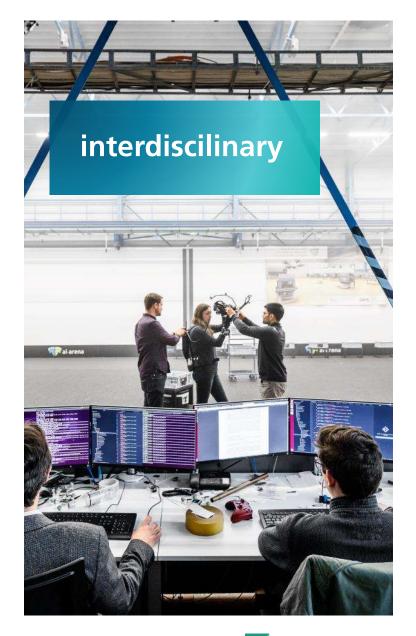
Prof. Dr.-Ing. Alice Kirchheim Hardware | Software 100% Management
Prof. Dr. Dr. h.c. Michael Henke
Processes | Organisation



































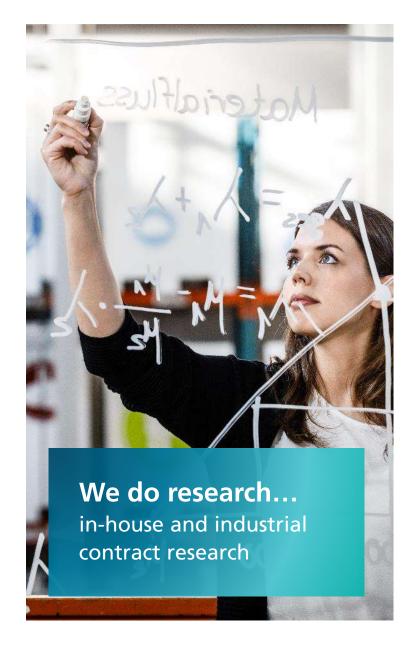
















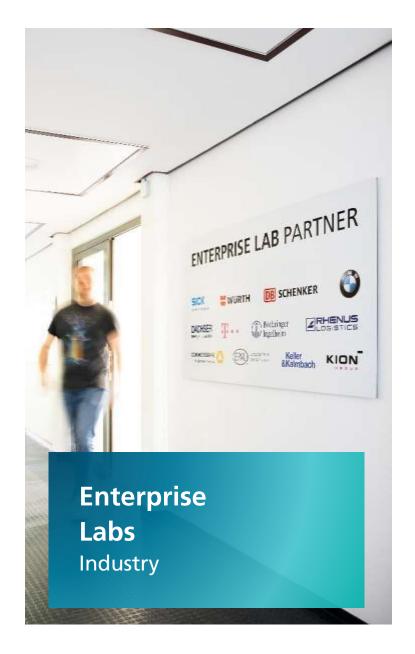




Open



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Fraunhofer-Gesellschaft

~ 32.000 employees

76 institutes

and research institutions

3.4 billion

research volume



Fraunhofer IML, Dortmund

~ 400

employees

~ 300

graduate students and student assistants

~ 55 million

turnover, 30% of which is made with industrial partners



> 55 million €

budget 2023

~ 700

employees **(12/2023)**

about 600 projects

per year

~ 30%

of the budget is made with industrial partners

~ 850,000 h

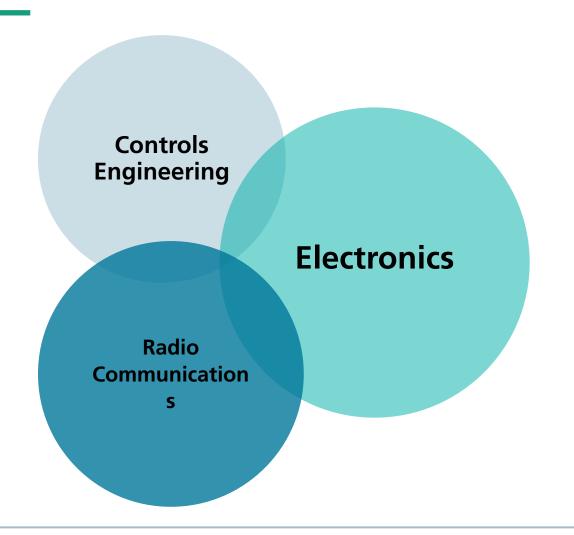
by order of logistics research (2023)





Department of IoT and Embedded Systems

Our Focal Points









The evolution of autonomous robots

The evoBOT® will serve a wide range of applications. By combining the individual capabilities of previous systems, the evoBOT overcomes the limitations of conventional and highly specialised robot systems available on the market.

From vision to prototype

The development of the evoBOT® began with the vision of developing a powerful robot system that is reduced to the essentials and at the same time has a wide range of capabilities. These include, for example, transporting, pulling and pushing goods and load carriers, as well as manipulating, picking up and placing on different levels, including the floor.

Outstanding controls

The principle of the inverse pendulum without external counterweight enables operation in the tightest of spaces and gradients. The pneumatic tyres also ensure movement on uneven surfaces such as gravel and outdoor areas even without a damping chassis. The control is independent of the load to be moved.











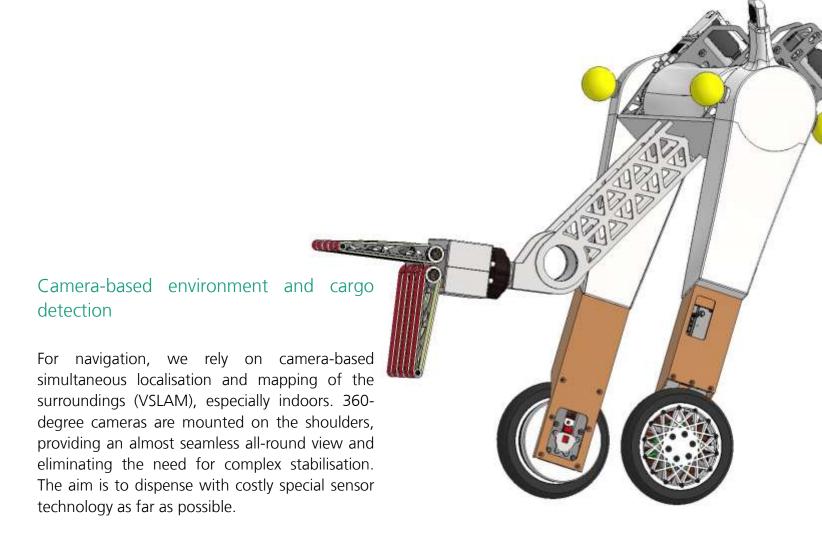




evoBOT® - Technical finesse

State of the art

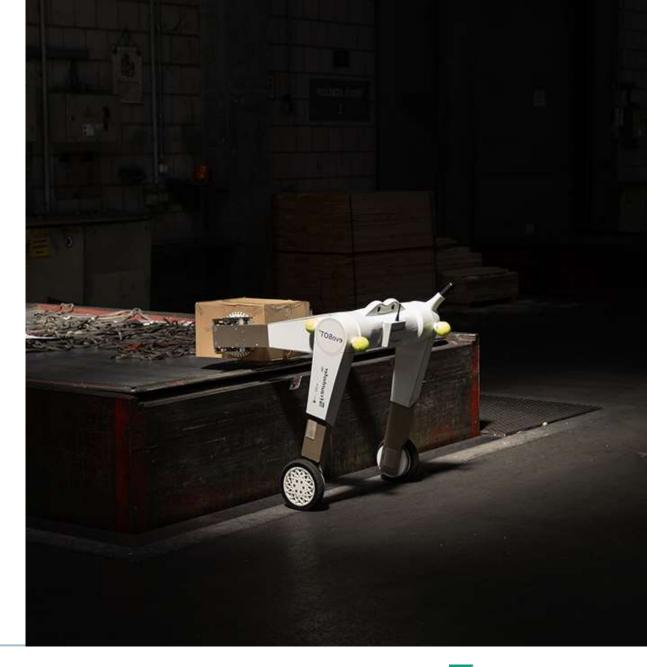
During development, emphasis was placed on hardware components that are state of the art in terms of precision, efficiency and dynamics. At the same time, the focus was on cost efficiency by reducing complexity and minimising the use of actuators, sensors and materials.





Key facts technical

- Scalable size
- Length: min. 192 mm
- Width: min. 785 mm
- Height: min. 925 mm
- 50 kg weight
- 60 km/h top speed
- 35 kg lifting capacity
- 100 kg load capacity





Key facts

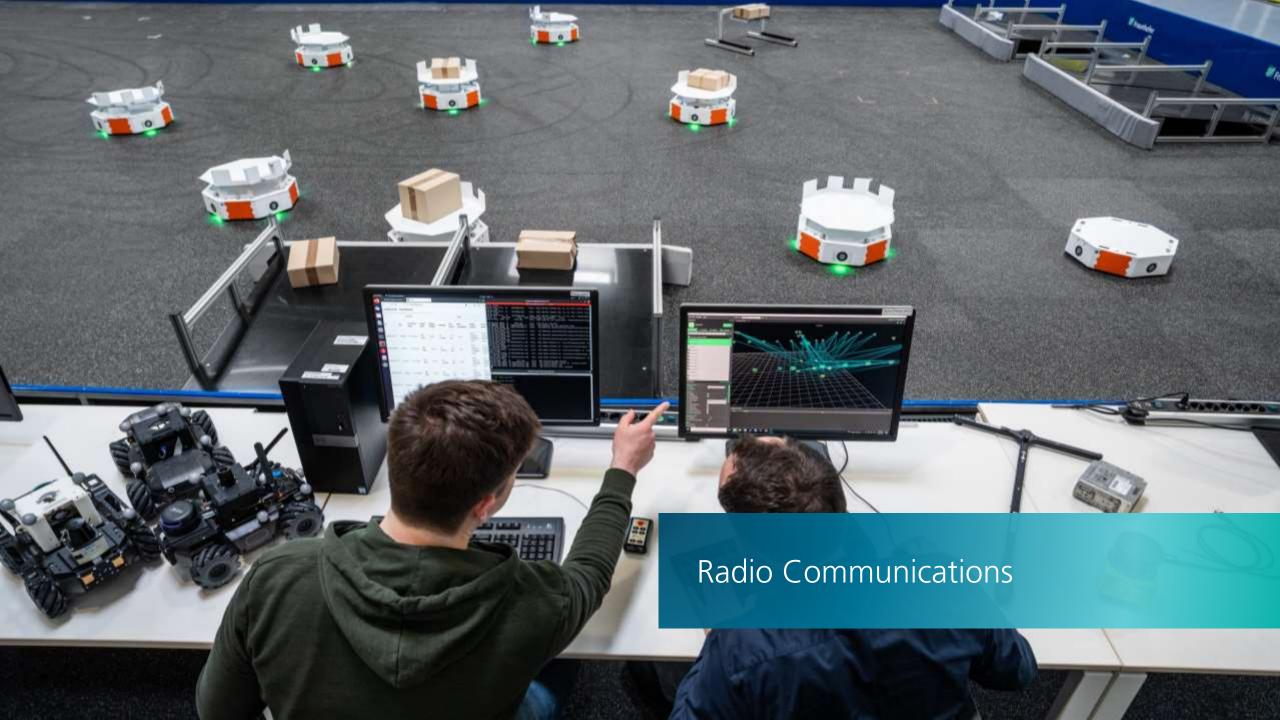
operational

- Outstanding control quality leads to high flexibility
- Modular design
- Easily scalable
- Excellent power-to-weight ratio (up to 2:1)
- Small footprint (especially in curves)
- High speeds
- Pick-up from the ground
- Variable transfer height
- Collaboration capability with people and machines
- Low energy consumption in static state
- Camera-based environment detection (VSLAM)

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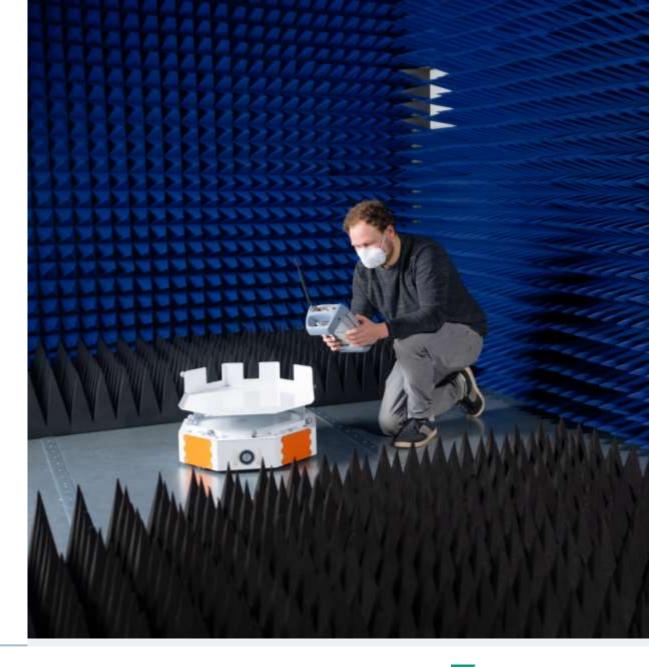




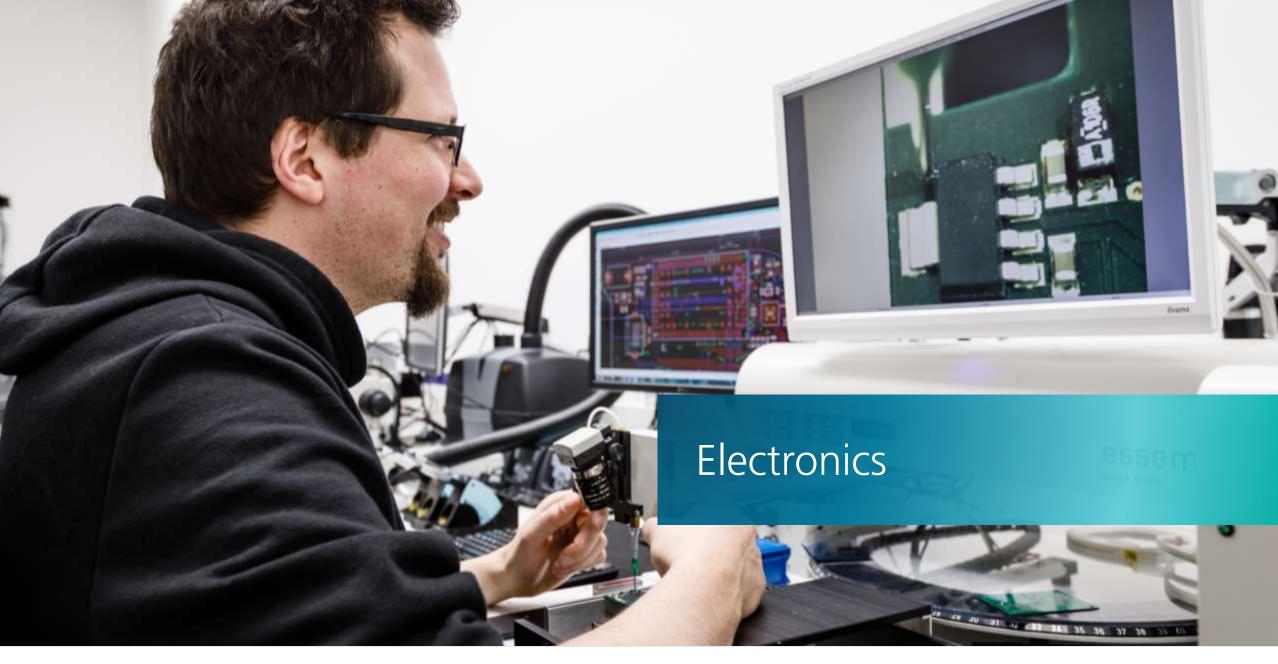
Radio communications

Connecting worlds

- **R&D** in **5G** and **6G** technologies
- **Custom-made antenna design**
- In-house testing on:
 - Electromagnetic capability
 - Antenna performance
 - Efectuation of components and structures
- Implementation of digital network twins







Embedded Engineering

in hardware and software

- **Consulting and design solutions**
- From conceptual design to pre-series production
- In-house development and small scale production of pcbs
- **Design follows function concepts for molding** enclosures
- Low power and low cost concepts for electronic components (e.g. IoT-devices)



